

IMPS 2017

# Modelling smooth and sudden changes in temporal dynamics of (V)AR-models

Casper Albers & Laura Bringmann

University of Groningen

[www.casperalbers.nl](http://www.casperalbers.nl) [c.j.albers@rug.nl](mailto:c.j.albers@rug.nl) Twitter: CAAL



# The basic AR(1) model

- Series of (psychological) measurements  $y_1, \dots, y_T$ .
- Simplest form of the model:

$$y_t = \mu + \phi y_{t-1} + \varepsilon_t, \quad (t = 2, \dots, T)$$

- Assume (for now) stationarity ( $|\phi| < 1$ ) and  $\varepsilon_i \sim N(0, \sigma^2)$

# The basic AR(1) model

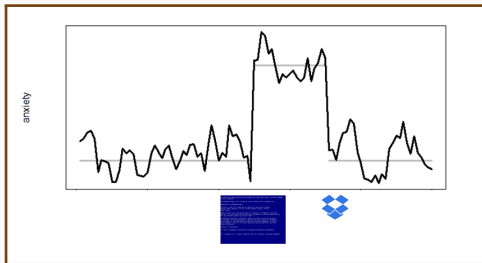
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- Assume (for now) stationarity ( $|\phi| < 1$ ) and  $\varepsilon_i \sim N(0, \sigma^2)$
- Here,  $\mu$  and  $\phi$  are fixed: they can't change.
- But people **do** change.

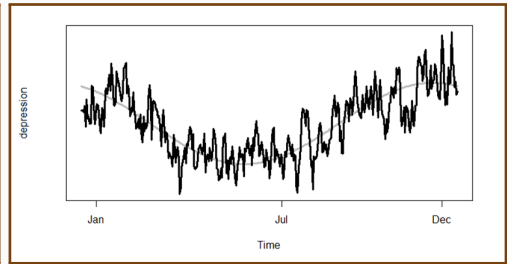
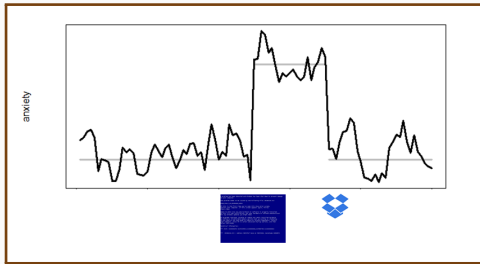
# Two types of change in AR(1) models

## 1. Sudden change



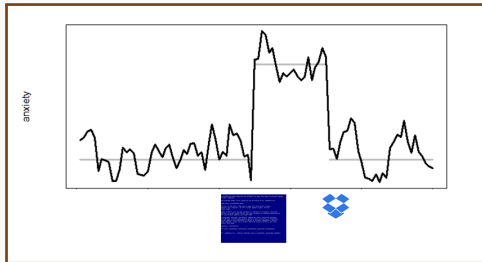
## Two types of change in AR(1) models

1. Sudden change
2. Smooth change



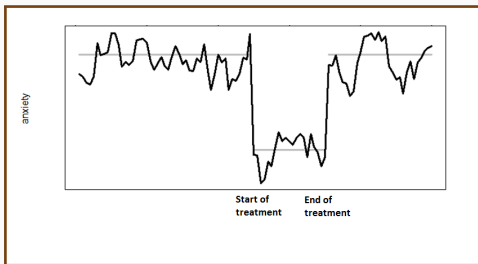
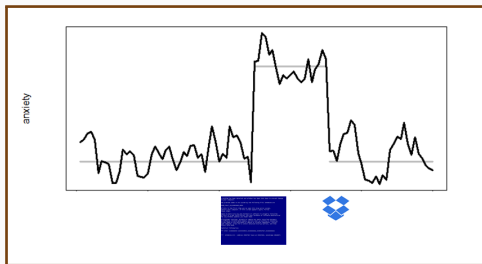
# Two types of sudden change

1. Sudden change at a **unknown** moment



# Two types of sudden change

1. Sudden change at a **unknown** moment
2. Sudden change at an **known** moment



# Goal of this talk

Thus, the dynamics in an AR(1) model can change

- Suddenly – at known moment(s)
- Suddenly – at unknown moment(s)
- Smoothly – (all the time)

(Many) models for **one of these** cases already exist. A model that combines these three cases in one is new.

**My goal of the day: to introduce this model to you**



# Models for sudden change

Many different models exist, e.g.

- Markov switching (regime change) models (next slide)
- Models from in Statistical Quality Control (e.g. the CUSUM procedure; Page, 1954)
- Models from Deep Learning (e.g. Krylov subspace models; Ide & Tsuda, 2007)
- Models from Machine Learning (e.g. relative density-ratio method; Sugiyama, Suzuki, & Kanamori, 2012)
- ..... (really, a *lot* of alternatives)

# Regime Switching Models

- Use dummy-variable

$$D_{i,t} = \begin{cases} 0 & \text{in regime 0 at time } t < i \\ 1 & \text{in regime 1 at time } t \geq i \end{cases}$$

for some  $i$ .

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- Then apply model

$$y_t = \mu_{D_{i,t}} + \phi y_{t-1} + \varepsilon_t, \quad (t = 2, \dots, T) \quad \text{or}$$

$$y_t = \mu_{D_{i,t}} + \phi_{D_{i,t}}(y_t - \mu_{D_{i,t-1}}) + \varepsilon_t, \quad (t = 2, \dots, T)$$

with  $\mu_0 \neq \mu_1$  (Hamilton, 1989)

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- Straightforward if  $i$  known. Apply HMM to find  $i$  when unknown.

## Model for smooth change

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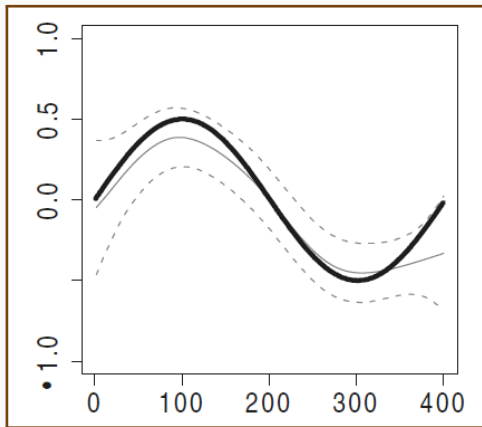
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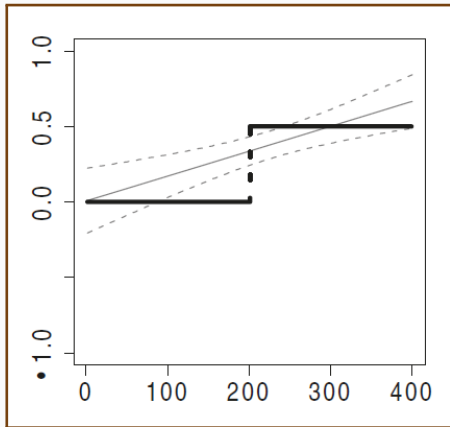
$$y_t = \mu_t + \phi_t y_{t-1} + \varepsilon_t$$

- $\mu_t$  and  $\phi_t$  not fixed, yet are only allowed to vary smoothly:  
 $\mu_t \approx \mu_{t+1}$  and  $\phi_t \approx \phi_{t+1}$
- This is achieved by using **Generalized Additive Models** (Hastie & Tibshirani, 1990) with thin-plate splines; and the R-package *mcgv* (Wood, 2011)

## TV-AR model for smooth change



works great



doesn't work



## Our model – confirmatory analyses

Basic idea of our TV-AR-RS model:

Combine TV-AR's smooth parameters with Hamilton's RS idea:

$$y_t = \mu_t + \mu_{D_{i,t}} + (\phi_t + \phi_{D_{i,t}}) \times y_{t-1} + \varepsilon_t$$

(with  $\mu_0 = \phi_0 = 0$ )

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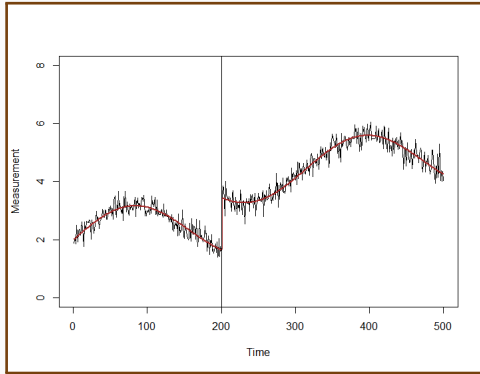
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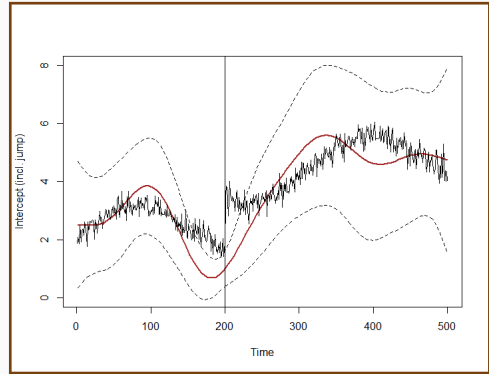
(with  $\mu_0 = \phi_0 = 0$ )

*mcgv*-package provides curves for  $\mu_t$  and  $\phi_t$  including CI, and point estimates for  $\mu_D$ ,  $\phi_D$  including SE, and model fit statistics. All you need.

# TV-AR-RS model – confirmatory analyses – example



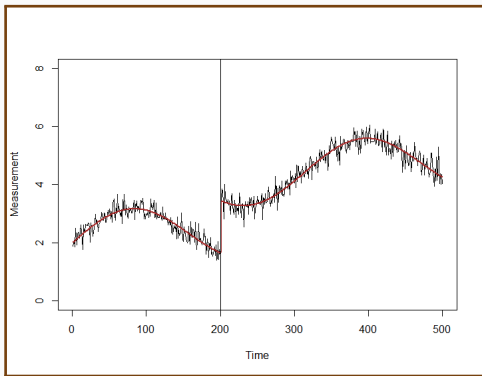
Simulated data



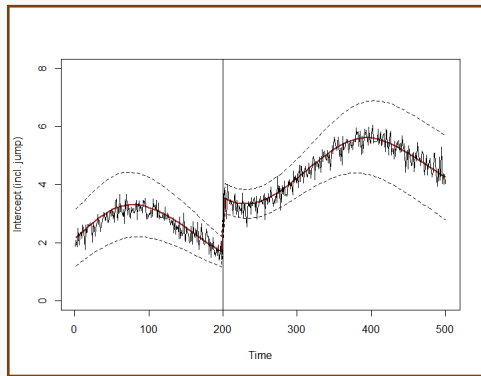
TV-AR model

TV-AR model: AIC = 173.42

# TV-AR-RS model – confirmatory analyses – example



Simulated data

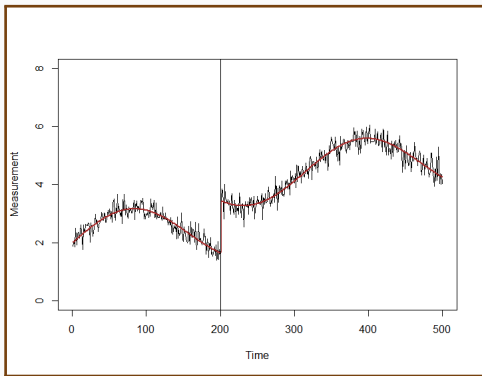


TV-AR-RS with correct jump

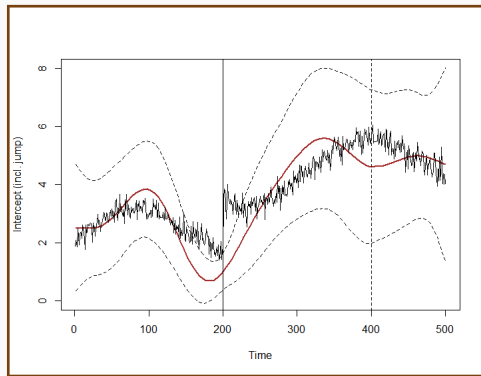
TV-AR model: AIC = 173.42

Correct TV-AR-RS model: AIC = 64.63,  $\hat{\mu}_1 = 1.88$  (sd=.13)

# TV-AR-RS model – confirmatory analyses – example



Simulated data



TV-AR-RS with correct jump

TV-AR model: AIC = 173.42

Correct TV-AR-RS model: AIC = 64.63,  $\hat{\mu}_1 = 1.88$  (sd=.13)

Incorrect TV-AR-RS model: AIC = 175.27,  $\hat{\mu}_1 = .04$  (sd=.13)

## TV-AR-RS model – exploratory analyses

Sketch of the algorithm:

1. Compute  $AIC^{(0)}$  for model  $y_t = \mu_t + \phi_t \times y_{t-1} + \varepsilon_t$

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3. Select  $i = \operatorname{argmin}_j AIC_j^{(1)}$
4. IF  $AIC_i^{(1)} < AIC^{(0)} - 10$  THEN select point  $i$  as new change point ELSE stop

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4. IF  $AIC_i^{(1)} < AIC^{(0)} - 10$  THEN select point  $i$  as new change point ELSE stop
5. Re-run steps 2 – 4 to find subsequent change points.

# Simulation results – I

Real AR(1) model: no jumps detected

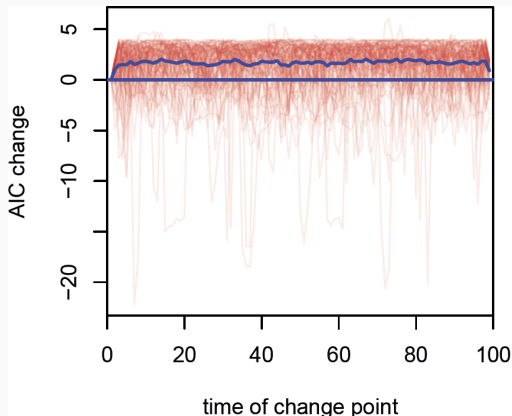
Intercept:



Autoregression:



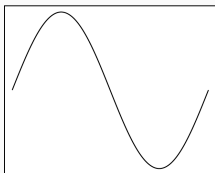
AIC change:



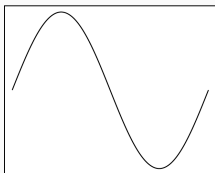
## Simulation results – II

Real TV-AR(1) model: no jumps detected

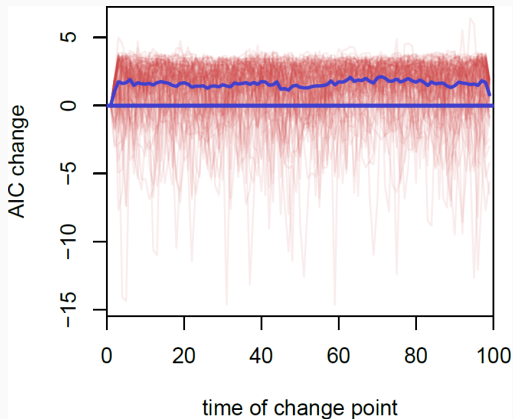
Intercept:



Autoregression:



AIC change:

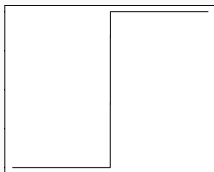


## Simulation results – III

TV-AR-RS(1) with  $\Delta\mu = 1\text{sd}$

$T=200$  is insufficient

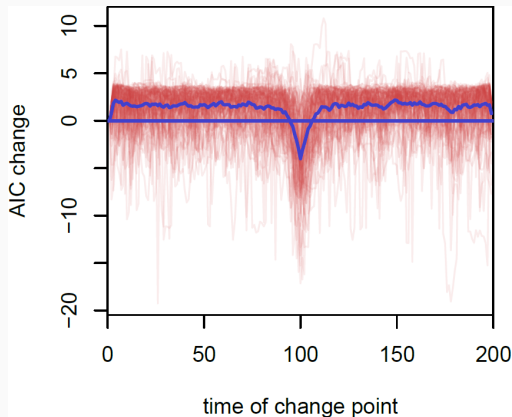
Intercept:



Autoregression:



AIC change:

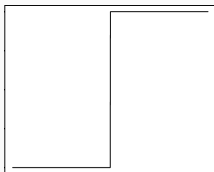


## Simulation results – IV

TV-AR-RS(1) with  $\Delta\mu = 2sd$

$T=200$  is sufficient

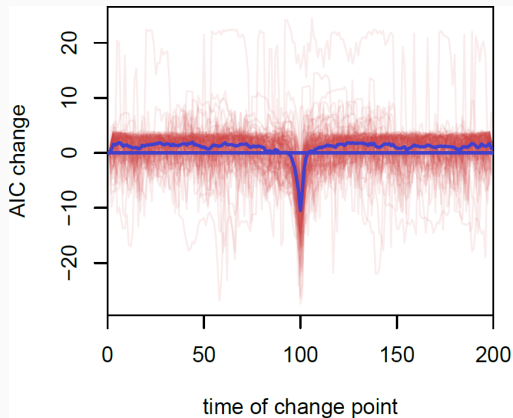
Intercept:



Autoregression:



AIC change:



## Simulation results – V

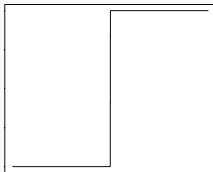
TV-AR-RS(1) with  $\Delta\phi = .3$

$T=200$  is insufficient

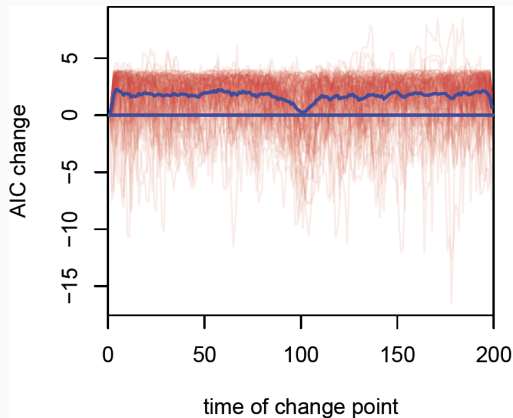
Intercept:



Autoregression:



AIC change:



# Simulation results – VI

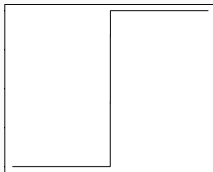
TV-AR-RS(1) with  $\Delta\phi = .7$

$T=200$  is sufficient

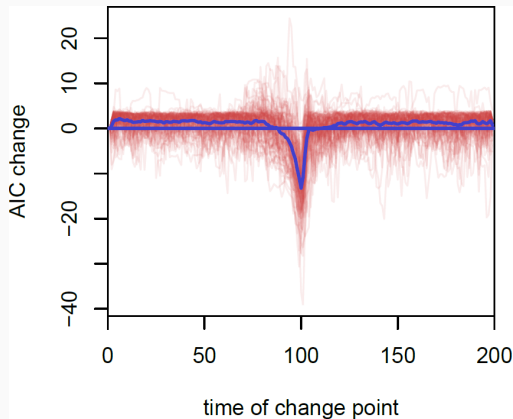
Intercept:



Autoregression:



AIC change:

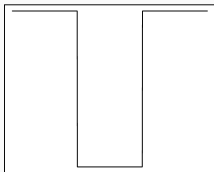




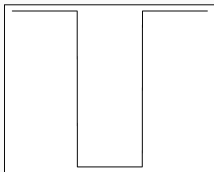
## Simulation results – VII

Finding multiple jumps? Yes we can!

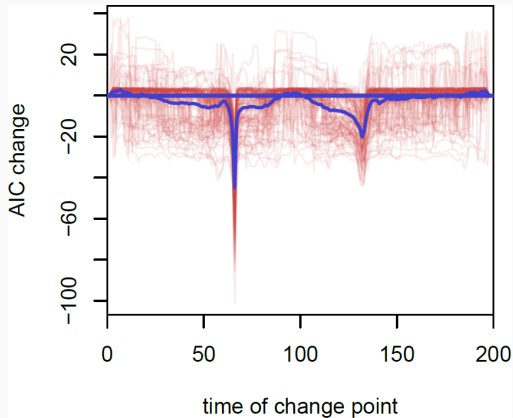
Intercept:



Autoregression:

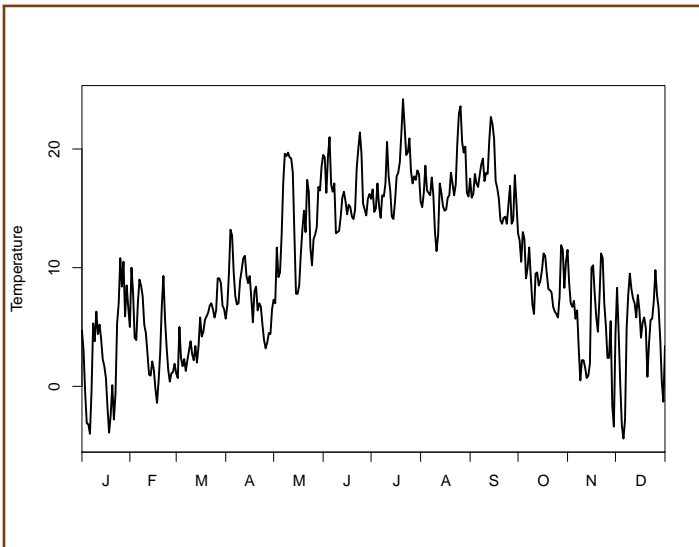


AIC change:



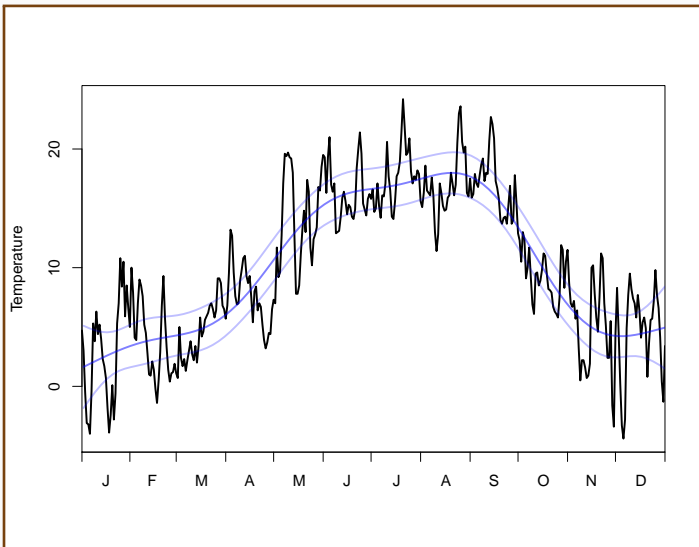
## Example: Daily temperature in Groningen/Eelde, 2016

# jumps    AIC

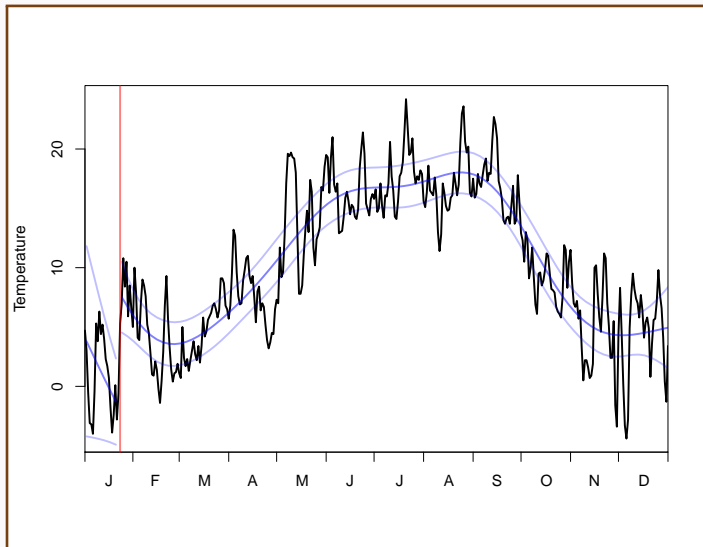


## Example: Daily temperature in Groningen/Eelde, 2016

# jumps	AIC
0	1849

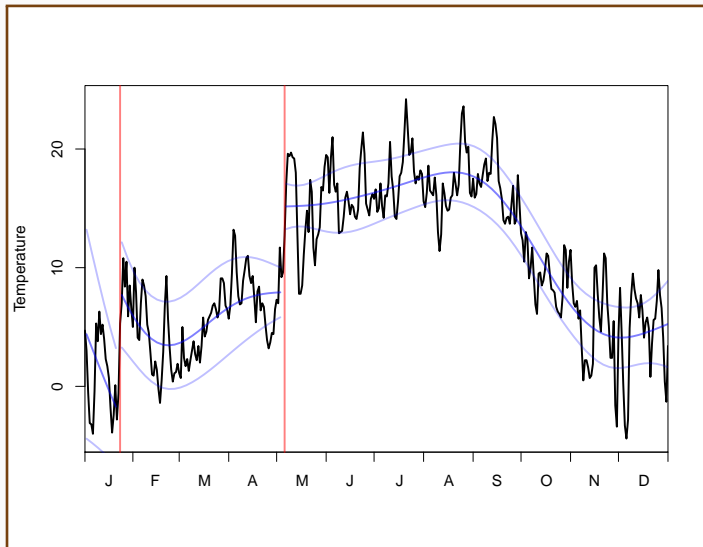


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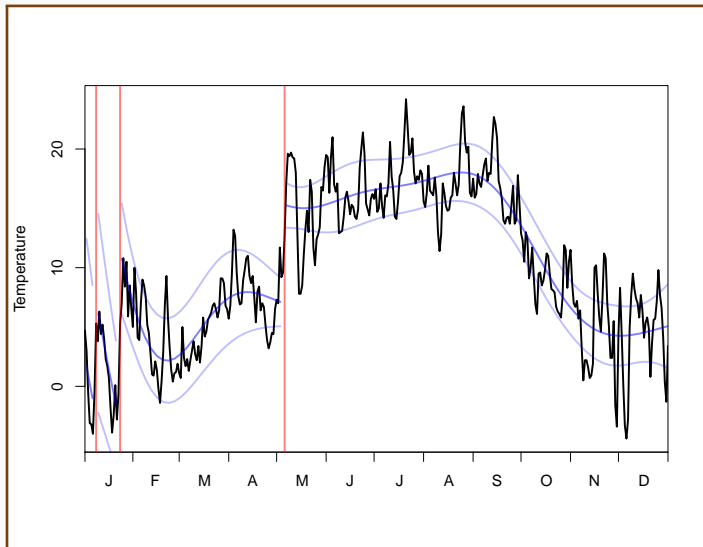
# jumps	AIC
0	1849
1	1814

## Example: Daily temperature in Groningen/Eelde, 2016



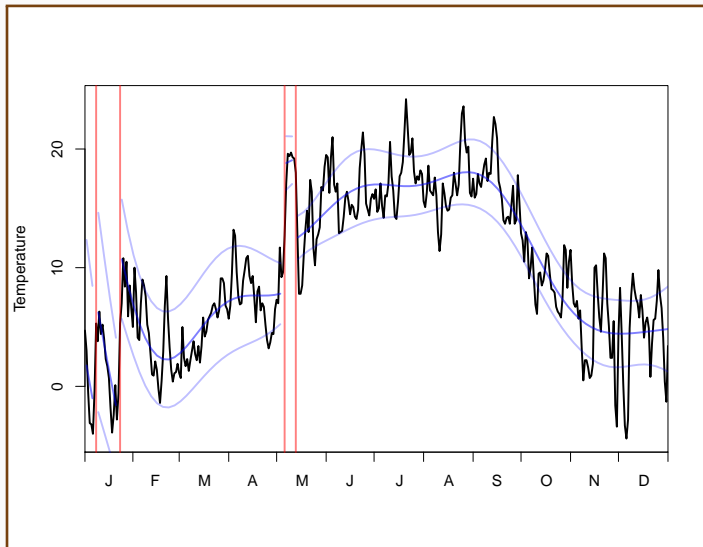
# jumps	AIC
0	1849
1	1814
2	1786

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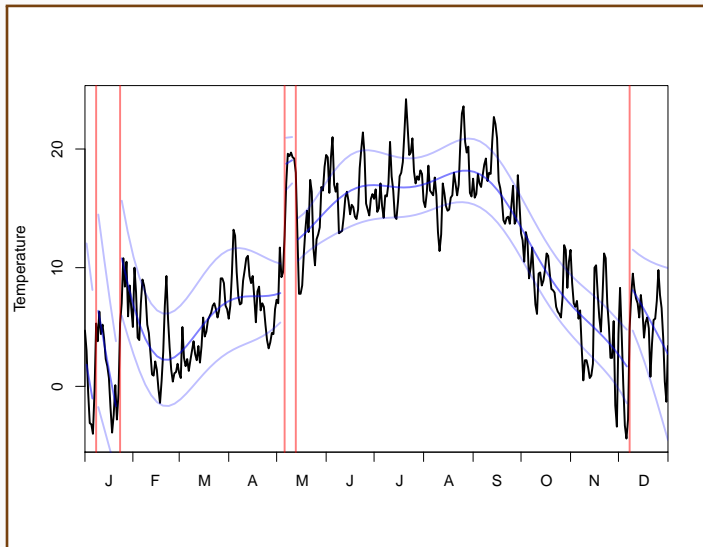
# jumps	AIC
0	1849
1	1814
2	1786
3	1747

## Example: Daily temperature in Groningen/Eelde, 2016



# jumps	AIC
0	1849
1	1814
2	1786
3	1747
4	1724

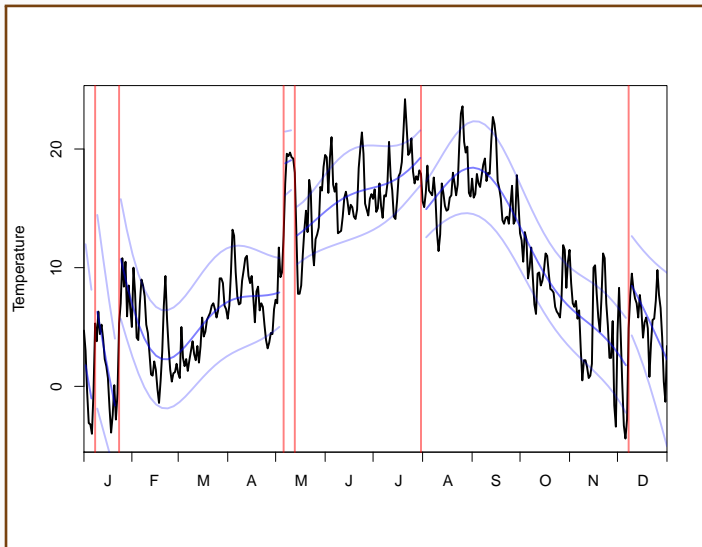
## Example: Daily temperature in Groningen/Eelde, 2016



# jumps	AIC
0	1849
1	1814
2	1786
3	1747
4	1724
5	1699

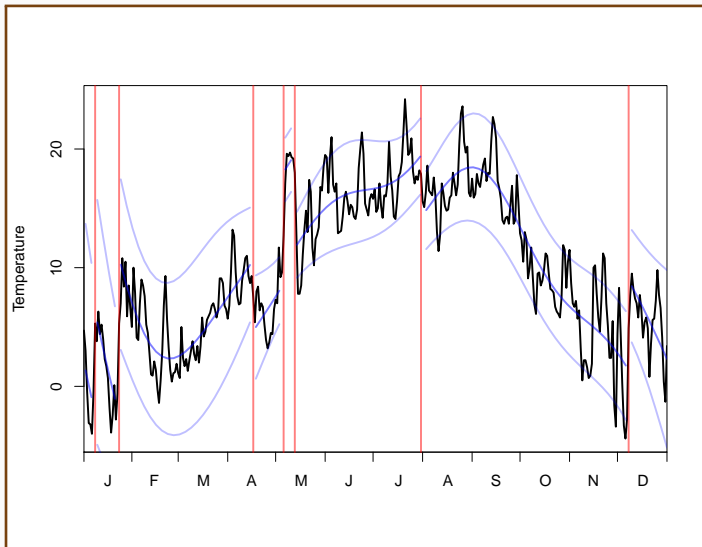


## Example: Daily temperature in Groningen/Eelde, 2016



# jumps	AIC
0	1849
1	1814
2	1786
3	1747
4	1724
5	1699
6	1683

## Example: Daily temperature in Groningen/Eelde, 2016



# jumps	AIC
0	1849
1	1814
2	1786
3	1747
4	1724
5	1699
6	1683
7	1665

# Conclusions

- We presented an elegant model that can deal with smooth and sudden change in dynamics.
- Can be used for both confirmatory and exploratory purposes
- Once finished, we will provide *R*-code
- Model works, but  $T$  needs to be large to exploratory detect sudden jumps
- Work in progress - still dotting the  $\iota$ 's...

## Key references:

- Bringmann, Hamaker, Vigo, Aubert, Borsboom, Tuerlinckx (2017), Changing Dynamics. Psychological Methods
- Hamilton (1989). A new approach to the economic analysis of nonstationary time series and the business cycle, Econometrica
- Royal Netherlands Meteorological Institute (KNMI), [www.knmi.nl](http://www.knmi.nl), for the data.